

# Package: terms (via r-universe)

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**Version** 1.0.2

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**Title** T-matrix for Electromagnetic Radiation with Multiple Scatterers

**Description** A set of Fortran modules/routines for T-matrix-based calculations of light scattering by clusters of individual scatterers.

**URL** <https://github.com/nano-optics/terms>,  
<http://nano-optics.ac.nz/terms/>

**BugReports** <https://github.com/nano-optics/terms/issues>

**Type** Package

**VignetteBuilder** knitr

**Encoding** UTF-8

**RoxygenNote** 7.2.3

**Depends** R (>= 3.5.0), rhdf5, cubs, dielectric, tidyverse, purrr, glue, dplyr, tibble, ggplot2

**Suggests** stringr, patchwork, gridExtra, egg, ggforce, DT, rgl, knitr, rmarkdown

**Repository** <https://nano-optics.r-universe.dev>

**RemoteUrl** <https://github.com/nano-optics/terms>

**RemoteRef** HEAD

**RemoteSha** 0aa3b67836d5fb6c84b27783b484078cf6d66821

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<code>cluster_positions</code>	<i>Clusters of particles</i>
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## Description

Defines various cluster geometries and exports in a format suitable for TERMS  
 Helix of particles  
 Chain of particles  
 Core-satellite cluster of spheres

## Usage

```

cluster_positions(
  N = 5,
  cl_fun = cluster_chain,
  radius = 50,
  label = "Au",
  ...,
  out = "",
  digits = 8
)

cluster_helix(
  N = 5,
  a = 10,
  b = 10,
  c = 50,
  R0 = 100,
  pitch = 200,
  delta = pi/5,
  delta0 = 0,
  hand = 1,
  ...
)

cluster_chain(
  N = 5,
  pitch = 500,
  a = 50,
  b = 30,
  c = b,
  rot = rotation_euler_passive(0, 0, 0)
)

cluster_satellite(N = 30, Rcore = 30, Rsat = 4, gap = 0.1, exclusion = 10, ...)

```

**Arguments**

N	number of particles
cl_fun	cluster function
radius	particle radius
label	particle material label
...	extra arguments passed to cl_fun
out	filename
digits	accuracy
a	semi-axis
b	semi-axis
c	semi-axis
R0	helix radius
pitch	chain pitch
delta	helix angle step
delta0	helix start angle
hand	helix handedness
rot	rotation matrix applied to each particle
Rcore	core radius
Rsat	satellite radius
gap	gap distance
exclusion	minimum exclusion distance for hc positions

**Value**

returns scatterers positions and sizes for an input file

**Functions**

- cluster\_positions(): write cluster positions to input file
- cluster\_helix(): helical cluster
- cluster\_chain(): linear chain cluster
- cluster\_satellite(): core-satellite cluster

**Examples**

```
cluster_positions()
cluster_helix()
cluster_chain()
cluster_satellite()
```

**Description**

Matrix of equal sizes  
 Matrix of equal angles  
 Combined T-matrix index  
 T-matrix indices  
 Unpack T-matrix indices  
 Unpack T-matrix indices  
 Wrap staged matrices into a list of T-matrix like objects  
 Read T-matrix into long-format data.frame  
 Display staged matrix  
 Display T-matrix  
 Display prestaged matrix  
 Generate an incidence file for spherical cubature  
 Generate a dielectric function in suitable format for TERMS  
 Euler rotation matrix  
 Euler rotation matrix  
 Axis-angle rotation from Euler angles  
 Extend a range symmetrically about 0  
 Extract geometry information from input file  
 Wrap geometry information into a 'cluster' structure  
 Visualise a 'cluster' structure

**Usage**

```
equal_sizes(a, b, c, N)
equal_angles(phi, theta, gamma, N)
p_index(in1, in2)
indices(n_max = 3, n_part = 1)
unpack_indices(n_max = 3, j_max = 2)
readamat(f)
```

```
amat_to_tmatlist(a, n_max = 3, n_part = 2)

read_tmat(f, save = FALSE)

display_amat(l)

display_tmat(s)

display_prestaged(a, n_max = 3, n_part = 2, draw = TRUE)

export_cubature(q = cubs::cubs(N = 10, cubature = "lebedev"), out = "")

export_dielectric(m = dielectric::epsAu(seq(400, 800)), out = "")

rotation_euler_passive(phi, theta, psi)

rotation_euler_active(phi, theta, psi)

euler_to_axisangle(a, b, c)

symmetric_range(range)

get_geometry(input = "input")

cluster_geometry(ge)

visualise_rgl(cl, outfile = NULL, show_core = FALSE, ...)
```

### Arguments

a	Euler angle
b	Euler angle
c	Euler angle
N	number of particles
phi	Euler angle
theta	Euler angle
gamma	Euler angle
in1	index
in2	index
n_max	maximum order
n_part	number of particles
j_max	size of collective T-matrix
f	filename
save	store result as Rds file
l	list of T-matrices, from amat_to_tmatlist

<code>s</code>	T-matrices, from <code>read_tmat</code>
<code>draw</code>	logical, draw output
<code>q</code>	<code>data.frame</code> with angles and weights, from <code>cubs::cubs()</code>
<code>out</code>	filename
<code>m</code>	<code>data.frame</code> with wavelength and epsilon, e.g. from <code>dielectric::epsAu()</code>
<code>psi</code>	Euler angle
<code>range</code>	range (2-vector)
<code>input</code>	filename
<code>ge</code>	geometry, from <code>get_geometry</code>
<code>cl</code>	'cluster' object
<code>outfile</code>	optional output snapshot
<code>show_core</code>	display a core sphere if 'R0' field present
<code>...</code>	additional parameters passed to <code>rgl.ellipsoids</code>

## Functions

- `equal_sizes()`: equal sizes
- `equal_angles()`: equal angles
- `p_index()`: p-index
- `indices()`: indices
- `unpack_indices()`: unpack indices
- `readamat()`: unpack indices
- `amat_to_tmatlist()`: wrap staged matrices
- `read_tmat()`: read T-matrix
- `displayamat()`: display staged matrix
- `display_tmat()`: display T-matrix
- `display_prestaged()`: display prestaged matrix
- `export_cubature()`: export a spherical cubature
- `export_dielectric()`: export a dielectric function
- `rotation_euler_passive()`: passive rotation matrix
- `rotation_euler_active()`: active rotation matrix
- `euler_to_axisangle()`: axis-angle rotation
- `symmetric_range()`: symmetric range
- `get_geometry()`: extract geometry information from input file
- `cluster_geometry()`: wrap geometry information obtained from input file
- `visualise_rgl()`: rgl visualisation of a cluster

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extract_time	<i>Extract timings from log files</i>
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## Description

Parses a log file to extract timing information from subroutines (verbosity-dependent)

## Usage

```
extract_time(log = "log")
```

## Arguments

log                    filename

## Value

returns a tibble of timings

## Functions

- `extract_time()`: extract timings from log files

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sample_fibonacci	<i>sample_fibonacci</i>
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## Description

Fibonacci coverage of a sphere

## Usage

```
sample_fibonacci(N = 301)
```

## Arguments

N                    number of points

## Details

Produces a set of points that covers rather uniformly the unit sphere with N points with a spiral-like pattern based on a Fibonacci sequence

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<code>store_xsec</code>	<i>Reshape cross-section results into a convenient format for post-processing and plotting</i>
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## Description

Read and store plain text cross-sections

Extracts commonly-used information from a HDF5 file storing far-field cross-sections (Mode=2), and reshapes the data into long-format data.frames suitable for plotting

Extracts partial absorption cross-sections from a HDF5 file storing far-field cross-sections (Mode=2), and reshapes the data into long-format data.frames suitable for plotting

## Usage

```
store_xsec(..., out = "xsec.rds")
consolidate_xsec(hdf5, verbose = TRUE, ...)
consolidate_partials(hdf5, verbose = TRUE)
```

## Arguments

...	extra arguments passed to the final list
out	output Rds filename
hdf5	filename
verbose	logical: print attributes

## Value

returns a list containing data.frames in long format

## Functions

- `store_xsec()`: store plain text cross-sections
- `consolidate_xsec()`: consolidate cross-sections
- `consolidate_partials()`: consolidate partial absorption cross-sections for multilayered spheres

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x3d_scene	<i>Interactive display of cluster geometries</i>
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## Description

Displays a cluster in X3D format

## Usage

```
x3d_scene(  
  cl,  
  viewpoint = c(0, 0, 100),  
  orientation = NULL,  
  width = "300px",  
  height = "300px",  
  scale = 100,  
  ...  
)
```

## Arguments

cl	cluster
viewpoint	viewpoint position (3-vector)
orientation	optional viewpoint orientation (axis-angle vector: x,y,z,angle)
width	display width
height	display height
scale	size of axes
...	extra arguments passed to cluster_to_x3d

## Value

returns X3D object to embed in a html document with suitable X3D support

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